





# About the survey

The General Lighthouse Authorities of the United Kingdom and Ireland (GLA), are conducting a short survey to gauge the current and future use of their Differential Global Positioning System (DIFFERENTIAL GPS) service.

The GLA operate 14 DIFFERENTIAL GPS reference stations which provide corrections to GPS (single frequency) enabling greater positional accuracy and integrity in the user's position. The survey results will be used by the GLA to assess this service in relation to the current and future user needs. More information on the GLA DIFFERENTIAL GPS system and other related technologies is provided in the annex.

# Data Protection

The survey is being conducted by the tri-GLA Research and Radionavigation Directorate (R&RNAV). R&RNAV is not a legal entity in itself. It works on behalf of, and reports to, all three of the General Lighthouse Authorities that cover the British Isles and some associated territories: that is Trinity House, the Northern Lighthouse Board and the Commissioners of Irish Lights. Trinity House provides the legal framework within which R&RNAV works: as such the legal notices provided by Trinity House also cover R&RNAV. These notices can be found on the Trinity House website<sup>1</sup>.

The General Data Protection Regulation (GDPR) and UK Data Protection laws set out how data which could identify a person must be handled. This survey invites respondents to provide their name, email and phone number in Question 1. This question is optional and any data provided will be used by the tri-GLA Research and Radionavigation Directorate (operating within Trinity House) to contact the respondent in the unlikely event that further information is required. Respondents are free to leave this question blank if they wish.

The survey is being conducted to engage with end users to ascertain the requirements for future marine aids-to-navigation and therefore falls within the scope of a public task. All data received will be uploaded to the SurveyMonkey online survey website and will be retained in full until the end of April 2019. Before or on that date, all data will be deleted from the website and only the anonymised results will be retained within the Trinity House document management system. Information on how SurveyMonkey securely holds data and how it complies with GDPR can be found on its website (https://www.surveymonkey.com/mp/gdpr/).

Anonymised results from the survey will be consolidated into a report for consideration by the three GLAs, extracts of which may be presented to other interested parties, both nationally and internationally. No personal data will be shared and no automated decisions will be taken.

Respondents have the right to request the deletion or amendment of their survey once submitted. Any amendment or deletion requests will be actioned as soon as possible and should be sent to the survey coordinator – Dr Alan Grant (alan.grant@gla-rrnav.org). Should anyone wish to complain about any aspect of this survey they may contact the Trinity House Data Protection officer (data.protection@trinityhouse.co.uk) who will then investigate any complaint.

Finally, should any personal data be sent to us by a third party we will aim to provide you with the shared information, where relevant, within one month. We will also aim to inform you of the source that the personal data originated from and how we would like to use your personal data.

<sup>&</sup>lt;sup>1</sup> https://www.trinityhouse.co.uk/legal-notices

#### Completing the survey

It is important to understand that this is a survey about your use of the Differential service and not GPS / other Global Navigation Satellite Systems (GNSS).

The survey can be completed online at: <u>https://www.surveymonkey.com/r/29N3SX3</u>

Survey responses can be provided until 30<sup>th</sup> September 2018 and may be posted or emailed to the addresses below:

Post:	The Ge	Alan Grant 9 General Lighthouse Authorities of the UK & Ireland 9 Trinity House, The Quay, Harwich, Essex. CO12 3JW					email:	<u>requ</u>	ests@gla-rrna	<u>v.org</u>	
Q1) You	ur Details	s (optiona	al)								-
-	Name: isation: Phone: Email:										
Q2) Wh	at is you Master		position?	Navigating	Office	er at Sea		Oth	er: (please state	below)	,
Com	ments:										
Mariti	me: 🗆	] Nc	n-maritime ase describe	: 🗌 (see be e what you u	elow) ise the	No GLA DIF	t currentl	y used L GPS s			]
	Мс	onitoring	Genera of anchored ng off point	or which you Il navigation Pilotage d position(s) s of interest Please state)		inss (e.g	I	Dynam Comn	etc.): ic Positioning Surveying nercial fishing ler protection		
Q5) Plea	ase indic	ate how	important r	marine beaco	on DIF	FERENTIA	AL GPS is f	or the	se operations:		
		Monito		eneral navig Pilc hored positi	otage	Critical	Nice to	have	Not required		

Monitoring of anchored position(s)IPassenger ships standing off points of interestI

- Dynamic Positioning
  - Surveying
  - Commercial fishing
- Policing/border protection

Other (as above)

Q6) If you use Dynamic Positioning (DP) – which positioning systems do you use and what back-up systems do you have available?

Primary systems:	
Back-up systems:	

Q7) Which aspect of the GLA DIFFERENTIAL GPS service is most important to you? Please indicate in the comment box how you use the integrity or accuracy information.

Integrity:		Accuracy:		Both: 🗌		
Comments:						
Q8) Please provide c	letails of your vess	el				
Ship size (Gr	ross tonnage or ler	ngth):				
01110 0120 (01	-	type:				
	Ship	Flag:				
Q9) How many GPS receiver?	receivers on board	l are fitted w	vith or interfaced	with a DIFFE	RENTIAL	GPS
1:	□ 2: □	] More	than 2: 🛛	Not sure:		
Q10) Does your DIFF normal parameters)		eiver give ar	n indication of "u	nhealthy" (or	perating o	outside
	Yes: 🗆	Ν	lo: 🗆	N	ot sure:	
Comm	ients:					
Q11) Have you expe DIFFERENTIAL GPS s		gradations,	outages or other	such incident	ts with th	e GLA
	Yes: 🗆	No: 🗆	] Don't kr	now: 🗆		
Com	ments:					
Q12) Do you find the	e GLA DIFFERENTIA	AL GPS servi	ce useful?			
	Yes (please	cay why):		No (please so	an mpu).	
Comm		suy why.		NO (pieuse si	iy wiiyj.	
Q13) Do you use any as STARFIX, or Space America)) for either	Based Augmentat	tion Systems	s (EGNOS across I			
Yes (please gi	ive details): 🗌	Ν	o: 🗆			
Additional info	ormation :					
Q14) How much exp	erience do you ha	ve in using [	DIFFERENTIAL GP	S?		
0-	5 years: 🗌	5-10 yea	ors: 🗌 10 o	r more years:		
Q15) How many GNS	SS receivers are fit	ted to your	vessel?			
1	1: 🗆 2: 🗆	3: 🗆	4: 🗌 5	(or more): [		

Q16) Which satellite constellations do you use today? (tick all that apply)									
GPS:		GLONASS:		Galileo:		BeiDou:		Other:	
Q17) Which satellite constellations do you expect to use within the next 5-10 years? ( <i>Tick all that apply</i> )									all that
GPS:		GLONASS:		Galileo:		BeiDou:		Other:	
Q18) Do you expect to replace your (D)GNSS receiver within the next 5 years?									
		Yes: 🗆		No	<b>b</b> : □				
Q19) What would be the impact to your normal operations if the GLA DIFFERENTIAL GPS service was deactivated? ( <i>Please detail in comment box</i> )									
No impact:	□ S	ome impact:		Change	approach	n: 🗆		ternative NTIAL GP	s:
Comments:									
Q20) Please provide any additional information or relevant comments.									

Thank you for completing the GLA DIFFERENTIAL GPS survey!

#### Brief overview of GNSS, DIFFERENTIAL GPS and augmentation options

### Global Navigation Satellite Systems (GNSS)

Global Navigation Satellite Systems is the generic name given to satellite navigation systems such as GPS, GLONASS, Galileo and BeiDou. GPS and GLONASS were both launched in the mid-1990s and are military systems providing both military and civilian services. GPS is the most commonly used GNSS as the GLONASS system was underfunded for many years. Galileo and BeiDou are more recent constellations and are not yet fully operational.

All GNSS work on the principle that each satellite broadcasts a message with a known start time which the user's receiver captures and tags with a time of receipt. By assuming the message travels at the speed of light a range estimate (known as the pseudorange) to each satellite can be estimated. By estimating the location of each satellite on transmission, and repeating the process for multiple satellites, the user's receiver can then estimate the position of the receive antenna in relation to the modelled surface of the earth. Errors in satellite position estimate, message propagation time and the lack of a precise clock in the user's receiver all contribute to the GPS position error. Most GNSS use a common frequency, 1.575.42 MHz, known as L1, to enable interoperability.

The accuracy of the system has continued to improve, and while the GPS service documentation reports accuracy levels of 7.8m (95%), users generally achieve positional accuracies in the order of 3-5m (95%). All constellations are undergoing improvement programmes, with the current move to provide civilian users with data on different frequencies, which will allow some error sources to be mitigated.

GNSS does not provide real-time alerts (position integrity) to position errors or system failures. The systems are monitored but corrective action may take many hours to effect, during which the user must rely on comparison with other position sources to detect and adjust for any errors.

#### Marine radiobeacon differential corrections

Marine radiobeacon differential correction systems, sometimes known as IALA beacons, were devised in the mid-to-late 1990's primarily to provide position integrity and to improve position accuracy which at that time was circa 100 metres.

Marine radiobeacon differential services, such as the GLA DIFFERENTIAL GPS, work on the basis that receivers located at selected fixed monitoring sites, known as reference stations, calculate the difference in the estimated range to each satellite with the known calculated range to each satellite. The calculated difference is the total error introduced by the various estimates and inaccuracies in the system and is referred to as the pseudorange error. These errors will be common for users within the vicinity of the reference station and are broadcast to mariners over a 300 kHz radio transmission. The mariner's receiver applies the measured pseudorange errors as corrections to improve its accuracy estimate.

As each reference station is constantly comparing the estimated position of the reference station receiver to the known location, and the estimated range to each satellite is being checked to confirm they are within a set error bound, any position errors are highlighted in real-time and alerts are provided to mariners in the vicinity, within 10s, thereby providing system integrity.

Marine beacon DIFFERENTIAL GPS can provide position accuracies in the range of 1-3m (95%), depending on the users distance to the reference station (accuracy decreases with distance as the errors seen by the user and the reference station become uncorrelated).

The GLA marine radiobeacon differential network consists of 14 reference stations located around the United Kingdom and the Republic of Ireland. They currently provide corrections for GPS only, but the technology is developing to enable corrections to be provided for all GNSS in the future, should there be a requirement. The GLA is considering the future needs for this system, including whether there is any requirement for it at all.

# Satellite Based Augmentation Systems (SBAS)

Satellite Based Augmentation Systems (SBAS) is the generic name given to systems which provide GPS error correction information via satellites. Developed primarily for aviation, they use a network of ground reference stations which operate in a similar manner to marine reference stations described above to calculate corrections, but in this system the correction information is broadcast to the user on the L1 frequency via dedicated satellites.

There are several SBAS systems in operation, with the two most commonly considered systems being the United States Wide Area Augmentation System (WAAS) and the European Geostationary Navigation Overlay Service (EGNOS). Each has a dedicated network of reference stations positioned over large areas, for example most of North America and across Europe for WAAS and EGNOS respectively. Using the data received at the reference stations, they model corrections for different error sources, rather than considering them collectively, providing a wide-area correction for the region served. This approach means that they provide a constant accuracy performance over the larger region. As the performance of the GNSS is being monitored constantly, SBAS also provide integrity alerts.

Many maritime receivers are SBAS enabled, including some marine beacon DIFFERENTIAL GPS receivers and therefore care is often required to establish and understand which system is being used at any given time. SBAS systems are also evolving, with plans to provide corrections to other constellations in due course.